Shimaden, Temperature and Humidity Control Specialists





# BASIC FEATURES

- □ Multi-input and multi-range performance
- □ Large 20mm bright display (SR93)
- Readable from a distance and in a low light area
- □ 2-output heating and cooling control available
- □ RS232C or RS485 Interface (MODBUS / Shimaden) available
- □ Dust and splash proof front panel equivalent to IP66
- □ A wide selection of additional functions (optional) is available to suit various needs.

## **SPECIFICATIONS**

Display		PID (outpu	at 1) + PID (output 2)
<ul> <li>Digital display:</li> </ul>	Measured value (PV)/7 segments red LED	RA (revers	se action characteristic): Heating action
	4 digits	(OUT1) ar	nd cooling action (OUT2)
	Target set value (SV)/7 segments green	DA (direct	characteristic): 2-stage heating action
	LED 4 digits	<ul> <li>Type of control/rating:</li> </ul>	Contact/1a 240V AC 2A (resistive load)
<ul> <li>Display accuracy:</li> </ul>	$\pm (0.3\%FS + 1 \text{ digit})$		1.2A (inductive load)
1 5 5	Excluding reference contact temperature	(Common to Output 1 and 2):	SSR drive voltage/12V±1.5V DC
	compensation accuracy of thermocouple	1	(Maximum load current 30mA)
	input.		Current/4~20mA DC (Maximum load
	Accuracy of readings lower than -100°C of		resistance $600\Omega$ )
	thermocouples K, T, U inputs is $\pm 0.7\%$ FS.		Voltage/0~10V DC (Maximum load
	Accuracy guarantee not applicable to		current 2mA)
	$400^{\circ}C$ (752°F) and below of B	• Control output resolution:	Control output 1: approx. 0.0125% (1/8000)
	thermocouple.	e connor curpat resonancia	Control output 2: approx. 0.5% (1/200)
• Display accuracy main		• Control output 1	
Display accuracy main	$23^{\circ}\text{C} \pm 5^{\circ}\text{C} (18 \sim 28^{\circ}\text{C})$	Proportional band (P):	OFF, 0.1~999.9% (ON-OFF action by OFF)
<ul> <li>Display resolution:</li> </ul>	Depends on measuring range $(0.001, 0.01, 0.01)$	Integral time (I):	OFF, 1~6000 seconds
Display resolution:	0.1 and 1)	integral time (i).	(P or PD action by OFF)
Massured value display r	ange: -10%~110% of measuring range	Derivative time (D):	OFF, 1~3600 seconds
<ul> <li>Display updating cycle</li> </ul>		Derivative time (D).	(P or PI action by OFF)
		Set value function:	OFF, 0.01~1.00
<ul> <li>Action display/color:</li> </ul>	7 type, LED lamp display	ON-OFF hysteresis:	1~999 units (Effective when P=OFF)
	Control output (OUT1, OUT2)/Green	Manual reset:	$-50.0 \sim 50.0\%$ (Effective when I=OFF)
	Event (EV1, EV2)/Orange		Lower limit 0.0~99.9%, higher limit
	Auto tuning/Green	Tighei/lower innit output inniter.	$0.1 \sim 100.0\%$ (Lower limit value < Higher
	Manual control output (MAN)/Green		
	Set value bias, communication	Due a suti su stansta	limit value)
	(SB/COM)/Green	Proportional cycle:	$1 \sim 120$ seconds (for contact and SSR drive
Setting			voltage output)
<ul> <li>Setting method:</li> </ul>	By operating 4 keys ( 💿 , 🔍 , 🔺	• Control output 2 (option)	
	and $(ENT)$ on the	Proportional band (P):	OFF, 0.1~999.9%
front panel			(ON-OFF action by OFF)
• Target value setting ran	nge: Same as measuring range (within setting	Integral time (I):	OFF, 1~6000 seconds
	limiter)		(P or PD action by OFF)
• Setting limiter:	Individual setting for higher and lower	Derivative time (D):	OFF, 1~3600 seconds
~ 8	limits, any value is selectable within		(P or PI action by OFF)
	measuring range (Lower limit	Set value function:	OFF, 0.01~1.00
	value <higher limit="" td="" value)<=""><td>ON-OFF hysteresis:</td><td>1~999 units (Effective when P=OFF)</td></higher>	ON-OFF hysteresis:	1~999 units (Effective when P=OFF)
■ Input	value (Higher Hille value)	Dead band:	-1999~5000 units (Overlap with a negative
• Type of input:	Selectable from multiple (TC, Pt, mV),		value)
- Type of input.	voltage (V) and current (mA)	Higher/lower limit output limiter:	Lower limit 0.0~99.9%, higher limit
• Thermocouple:	B, R, S, K, E, J, T, N, PL II, Wre5-26 {U, L		0.1~100.0% (Lower limit value < Higher
• Thermocoupie.	(DIN 43710)}		limit value)
Input impedance:	500k <b>Ω</b> minimum	Proportional cycle:	1~120 seconds (for contact and SSR drive
External resistance tolera			voltage output)
Burnout function:	Standard feature (up scale)	<ul> <li>Manual control</li> </ul>	
Reference junction con		Output setting range:	0.0~100.0%
Reference Junction con	$\pm 1^{\circ}$ C (within the accuracy maintaining	Setting resolution:	0.1%
	range $(23 \pm 5^{\circ}C)$ )	Manual $\leftrightarrow$ auto switching:	Balanceless bumpless (within proportional
	$\pm 2^{\circ}$ C (between 5 and 45°C of ambient	-	range)
	·	<ul> <li>Soft start:</li> </ul>	OFF, 1~100 seconds
• R.T.D.:	temperature) Pt100/JPt100, 3-wire type	• AT point:	SV value in execution
Normal current:	0.25 mA		RA (reverse action characteristic)/DA
Lead wire tolerance:	$5\Omega$ maximum/wire (3 lead wires should	*	(direct action characteristic) switching by
Lead whe tolerance:			front key or communication
• Valta a mV	have the same resistance.)	With 2 outputs:	RA (heating/cooling)/DA (2 stage heating)
• Voltage mV:	-10~10, 0~10, 0~20, 0~50, 10~50,	• Isolation:	Contact output isolated from all.
V.	0~100mv DC		Analog output not insulated from SSR drive
V:	-1~1, 0~1, 0~2, 0~5, 1~5, 0~10V		voltage, current and voltage but insulated
Input impedance:	$500$ k $\Omega$ minimum		from others. (In case another output is also
• Current mA:	0~20, 4~20mA DC		SSR drive voltage, current or voltage,
Receiving impedance:	250 <b>Ω</b>		two outputs are not insulated from
• Input scaling function:	Scaling possible for voltage (mV, V) or		each other.)
~	current (mA) input	Event output (option)	
Scaling range:	-1999~9999 counts	• Number of event points:	2 points of EV1 and EV2
Span:	10~5000 counts	• Types:	Selectable from the following 9 types for
Position of decimal poi	e e	e Types.	EV1 and EV2:
	decimal point		No selection
<ul> <li>Sampling cycle:</li> </ul>	0.25 seconds	<u> </u>	Higher limit deviation
• PV bias:	-1999~2000 units		Lower limit deviation
• PV filter:	0~100 seconds		Outside higher/lower limit deviations
• Isolation:	Control input not insulated from system, set		
	value bias, and CT input but insulated from		Within higher/lower limit deviations
	others		Higher limit absolute value
Control			Lower limit absolute value
<ul> <li>Control mode</li> </ul>			Scaleover
With 1 output: Exper	t PID control with auto tuning function	—	Heater break/loop alarm
	everse action characteristic): Heating action	• Event setting range:	Absolute values (both higher limit and
	irect action characteristic): Cooling action		lower limit): Within measuring range
	t PID control with auto tuning function +		Deviations (both higher limit and lower
PID co			limit): -1999~2000 units
			Higher/lower limit deviations

	(within/outside): 0~2000 units	Data format:	8E1, 8E2, 8N1, 8N2
<ul><li>Event action:</li><li>Hysteresis:</li></ul>	ON-OFF action 1~999 units	Control code:	None
<ul> <li>Hysteresis:</li> <li>Standby action:</li> </ul>	Selectable from the following 4 types	Error check: Function code:	CRC-16 03H, 06H (Hex)
EV1 and EV2:	1 Without standby action.	Function code.	1) 03H, read data
2 ; 1 und 2 ; 2.	2 Standby when power is applied.		2) 06H, write data
	3 Standby when power is applied and	• Isolation:	Communication signals insulated from
	when SV value in execution is changed.		system, each input and each output.
	4 Control mode without standby action (No	Analog output (option)	
	alarm is output at the time of abnormal	• Number of output points:	1 point
• Output type/rating:	input). Contact (1a × 2 points common)/240V AC	• Type of analog output:	Selectable from measured value, target value (SV in execution), control output 1
• Output type/fatting.	1A (resistive load)		and control output 2.
• Output updating cycle:	0.25 seconds	• Output signal/rating:	$4 \sim 20 \text{mA DC/Maximum load resistance } 300 \Omega$
Heater break/heater loc		e uput signal futilig.	0~10V DC/Maximum load current 2mA
	n only for OUT1 (Selectable when output		$0~10mV$ DC/Output resistance $10\Omega$
type is contact or SSR drive		<ul> <li>Output scaling:</li> </ul>	Measured value, target value: Within
• Current capacity:	30A or 50A to be designated when CT is		measuring range (inversed scaling possible)
• Alarm action:	ordered. Heater current is detected by external CT		Control output 1 and 2 0.0~100.0%
• Alarmaction.	provided as an accessory.	• Output accuracy:	(inversed scaling possible) ±0.3% FS (with respect to displayed value)
	When heater break is detected while control	<ul><li>Output accuracy:</li><li>Output resolution:</li></ul>	Approx. 0.01% (1/10000)
	output is ON=Alarm output ON	• Output updating cycle:	0.25 seconds
	When heater loop alarm is detected while	• Isolation:	Analog output insulated from system and
	control output is OFF=Alarm output ON		inputs but not insulated from control output
<ul> <li>Current setting range:</li> </ul>	OFF, 0.1~50.0A (Alarm action is stopped		except contact output.
	by setting OFF)	General specifications	
<ul> <li>Setting resolution:</li> <li>Current display range:</li> </ul>	0.1A 0.0~55.0A	<ul> <li>Data storage:</li> <li>Environmental conditions f</li> </ul>	Non-volatile memory (EEPROM)
<ul> <li>Display accuracy:</li> </ul>	$\pm 2.0A$ (Sine wave at 50Hz)	Temperature:	-10–50 °C
	0.25 seconds (every 0.5 seconds) common	Humidity:	90% RH or less (no dew condensation)
	to ON and OFF	Height:	2000m from the sea level or lower
<ul> <li>Alarm retention mode:</li> </ul>	Selectable from lock (to retain) and real	Category:	П
	(not to retain).	Degree of pollution:	2
<ul> <li>Standby action:</li> </ul>	Selectable from without (OFF) and with	• Storage temperature:	-20–65 °C
• Compling avalat	(ON). 0.5 seconds	<ul> <li>Supply voltage:</li> </ul>	Either 100-240V AC±10% 50/60Hz or
<ul><li>Sampling cycle:</li><li>Isolation:</li></ul>	CT input not insulated from system and	• Power consumption:	24V AC/DC±10% to be designated. SR91: 100-240VAC 11VA maximum for
• Isolation.	other input but insulated from the others.	• Fower consumption.	AC; 6W for DC 24V; 7VA for AC 24V
Set value bias/DI (option)			SR92, SR93 and SR94: 100-240VAC
• Number of input points:	1 point		15VA maximum for AC; 8W for DC
• Setting range:	-1999–5000 units		24V; 9VA for AC 24V
<ul> <li>Action input:</li> </ul>	Non-voltage contact or open collector (level	<ul> <li>Input/noise removal ratio:</li> </ul>	50 dB or higher in normal mode (50/60 Hz)
• Minimum level retention time:	action) about 5V DC, 1mA maximum 0.15 seconds		130 dB or higher in common mode
<ul> <li>Minimum level retention time.</li> <li>DI types:</li> </ul>	1) None	• Applicable standards:	(50/60 Hz) Safety: IEC1010 and EN61010-1
• Di types.	2) SB; set value bias	• Applicable standards.	EMC: EN61326
	3) STBY; standby		RoHS compliance: EN50581
	4) ACT; control action characteristics	<ul> <li>Insulation resistance:</li> </ul>	Between input/output terminals and power
• Isolation:	Action input not insulated from system and		terminal 500V DC 20M $\Omega$ or above;
	other inputs but insulated from others		Between input/output terminals and
Communication functio			protective conductor terminal 500V DC
<ul><li>Type of communication:</li><li>Communication system:</li></ul>	RS-232C, RS-485 RS-232C : 3-line type half duplex system	• Dielectric strength:	$20M\Omega$ or above Between input/output terminals and power
• Communication system.	RS-485 : 2-line type half duplex system	• Dielectric strength.	terminal 2300V AC 1 minute; Between
	(RS-485 is of half-duplex multi-drop (bus)		power terminal and protective conductor
	system)		terminal 1500V AC 1 minute
• Communication distance:	RS-232C : The longest: 15 m	<ul> <li>Protective structure:</li> </ul>	Only front panel has dust-proof and drip-
	RS-485 : The longest: 500 m (depending on		proof structure equivalent to IP66.
	conditions)	<ul> <li>Material of case:</li> </ul>	PPO resin molding
<ul> <li>Number of connectable inst</li> </ul>			(equivalent to UL94V-1)
• Synchronization system:	RS-232: 1, RS-485: up to 31 Start-stop synchronization system	• External dimensions:	$H48 \times W48 \times D111$ (Panel depth: 100) mm
<ul> <li>Synchronization system.</li> <li>Communication speed:</li> </ul>	1200, 2400, 4800, 9600, 19200 bps		$H72 \times W72 \times D111$ (Panel depth: 100) mm
<ul> <li>Communication address:</li> </ul>	1~255		$H96 \times W96 \times D111$ (Panel depth: 100) mm
Communication delay time			$196 \times W48 \times D111$ (Panel depth: 100) mm
Communication memory mode:	EEP/RAM/r_E	• Mounting:	Push-in panel (one-touch mount)
• Communication protocol(1):		• Panel thickness:	1.0–4.0 mm
Data format:	7E1, 7E2, 7N1, 7N2, 8E1, 8E2, 8N1, 8N2	• Panel cutout:	SR91: H45 $\times$ W45 mm
Control code:	STX_ETX_CR, @_:_CR		SR92: H68 × W68 mm SR93: H92 × W92 mm
Communication BCC: Communication code:	Add, Add two's cmp, XOR, None ASCII code		SR93: H92 × W92 mm SR94: H92 × W45 mm
<ul> <li>Communication code.</li> <li>Communication protocol(2):</li> </ul>		• Weight:	SR94: H92 × W45 min SR91: Approximately 170 g
Data format:	7E1, 7E2, 7N1, 7N2		SR92: Approximately 280 g
Control code:	CRLF		SR93: Approximately 330 g
Error check:	LRC check		SR94: Approximately 240 g
Function code:	03H, 06H (Hex)		
	1) 03H, read data		
	2) 06H, write data		

<sup>2) 06</sup>H, write dataCommunication protocol(3): MODBUS RTU mode

ITEM		CODE					SPECIFICATIO	DNS			
SERIES	SR91-						MPU-Based Auto-Tuning PID Digital Controller, DIN H48 × W48 × D110mm				
							Thermocouple: B, R, S, K, E, J, T, N, PLII, W				
							R.T.D.: Pt100Ω /JPt100Ω				
		8 Multi input				Voltage: -10~10, 0~10, 0~20, 0~50,	For voltage and current input:				
							10~50, 0~100mV DC	Scaling Possible			
INPUT							Current (mA): 0~20, 4~20mA DC Range: -1999~9999				
		4					Receiving impedance: $250\Omega$	Span: 10~5000			
							Voltage (V): -1~1, 0~1, 0~2, 0~5,	Note: Inverse scaling			
		6					1~5, 0~10V DC	is not possible			
			X				Contact: 1a, Contact capacity: 240V AC 2.54	Vresistive load			
			Y-				Proportional cycle: 1~120 sec.				
							Current: 4~20mA DC				
			1-				Load resistance: $600\Omega$ max.				
CONTROL OUTPUT (1)					SSR drive voltage: 12V±1.5V DC/30mA max	κ.					
	P-					Proportional cycle: 1~120 sec.					
			N				Voltage: 0~10V DC				
			V-				Load current: 2mA max.				
			90-				100~240V AC±10%, 50/60Hz				
POWER S	UPPLY	IPPLY 08-				24V AC/DC±10%, 50/60Hz					
				0			None				
EVENT OU	JTPUT (OP	TIO	N)	1			Contact output (2a) Ev1, Ev2: 240V AC 1A/re	esistive load			
					Ν		None				
							Contact: 1a, Contact capacity: 240V AC 2.54	Vresistive load			
					Y		Proportional cycle: 1~120 sec.				
							Current: 4~20mA DC				
	Contro	<del>ا</del> م ا	mut (0)		I		Load resistance: $600\Omega$ max.				
	Contro	out	pul (2)		Р		SSR drive voltage: 12±1.5V DC/30mA max.				
					Р		Proportional cycle: 1~120 sec.				
							Voltage: 0~10V DC				
OPTION					V		Load current: 2mA max.				
					4		Current setting range: 0.1~30.0A (with CT 30	Note: Avaialble only			
	Heater	hro	ok olorm		1		Current setting range. 0.1~30.0A (with C1 30	when control output (1)			
	neater	Diea	ak alarm		~		Current potting range: 0.1 E0.04 (with OT E	is Y or P and when event			
					2		Current setting range: 0.1~50.0A (with CT 50	output is selected.			
					3		Voltage: 0~10mV DC, Output resistance: 10	Ω			
	Analog	out	put		4		Current: 4~20mA DC, Load resistance: 300	2 max.			
					6		Voltage: 0~10V DC, Load current: 2mA max				
	Comm	unica	ation		5		RS-485 (Shimaden standard protocol / MOD	BUS (RTU / ASCII))			
	SV Bia				8		DI (set value bias, STBY, or ACT) 1 point, Nor	n-voltage contact or Open collector input			
	SVBIA	5/L	//		0		Open collector input rating: approx. 5V/1mA				
						0	Without				
REMARKS	•					9	With (Please consult before ordering.)				

### Note:

When you purchase a two-output type controller and use it in a one output capacity, larger overshooting or undershooting may happen as a result of integral operation. Therefore, we recommend you to choose a one-output type.

The cause of the above-mentioned problem is that the positional relationship between the proportional band (PB) and the set value (SV) of a one-output type controller differs from that of a two-output type.

ITEM			C	CODE	E					SPECIFICATIONS		
SERIES	SR92-							MPU-Based Auto-Tuning PID Digital Controller, DIN H72 $\times$ W72 $\times$ D110mm				
		8	м	ulti ir	nput					Thermocouple: B, R, S, K, E, J, T, N, PLII, Wre5- R.T.D.: Pt100 $\Omega$ /JPt100 $\Omega$ Voltage (mV): -10~10, 0~10, 0~20,	-26 {U, L (DIN 43710)} For voltage and current input:	
INPUT											Scaling Possible	
		4								Current (mA): 0~20, 4~20mA DC	Range: -1999~9999	
		<u> </u>									Span: 10~5000	
		6								• • • • • • •	Note: Inverse scaling	
				_						0~10V DC Input resistance: 500kΩ min.	is not possible.	
			Y-							Contact: 1a, Contact capacity: 240V AC 2A/resis	tive load	
				-						Proportional cycle: 1~120 sec. Current: 4~20mA DC		
			I-							Load resistance: $600\Omega$ max.		
CONTRO		(1)								SSR drive voltage: 12V±1.5V DC/30mA max.		
			P-							Proportional cycle: 1~120 sec.		
										Voltage: 0~10V DC		
			V-							Load current: 2mA max.		
				N-						None		
				Y-						Contact: 1a, Contact capacity: 240V AC 2A/resis	tive load	
				1-						Proportional cycle: 1~120 sec.		
CONTROL		(2)		1-						Current: 4~20mA DC		
(OPTION)		(ک)								Load resistance: $600\Omega$ max. (RA when shipped)		
( )				P-						SSR drive voltage: 12V±1.5V DC/30mA max.		
				-						Proportional cycle: 1~120 sec.		
				V-						Voltage: 0~10V DC		
					00					Load current: 2mA max.		
POWER S	UPPLY				90- 08-					100V~240V AC±10%, 50/60Hz 24V AC/DC±10%, 50/60Hz		
					00-	0				None		
						0				Event output (2a) Ev1, Ev2		
						1				Contact capacity: 240V AC 1A/resistive load		
EVENT O	UTPUT/ BREAK ALA	RM	(Of	PTIO	N)	2				Event output (Ev1) + Heater break alarm (with CT3	0A) Note: Available only when control output (1)	
						3				Event output (Ev1) + Heater break alarm (with CT5	0A) is Y or P is selected.	
							0			None		
ANAI OG	OUTPUT (C	PTI	ON'	)			3			Voltage: 0~10mV DC, Output resistance: $10\Omega$		
			0.1	,			4			Current: 4~20mA DC, Load resistance: 300Ω ma	IX.	
							6	-		Voltage: 0~10V DC, Load current: 2mA max.		
							-	0		None		
	ICATION OF	2 01	/ Bi	ae/N				5 7		RS-485 (Shimaden standard protocol / MODBUS RS-232C (Shimaden standard protocol / MODBU	1 11	
		101	ים י	u3/D		10	11)	1		DI (set value bias, STBY, or ACT) 1 point, Non-voltage		
								8		Open collector input rating: approx. 5V/1mA max		
								_	0	Without		
REMARKS	5								9	With (Please consult before ordering.)		
9						,						

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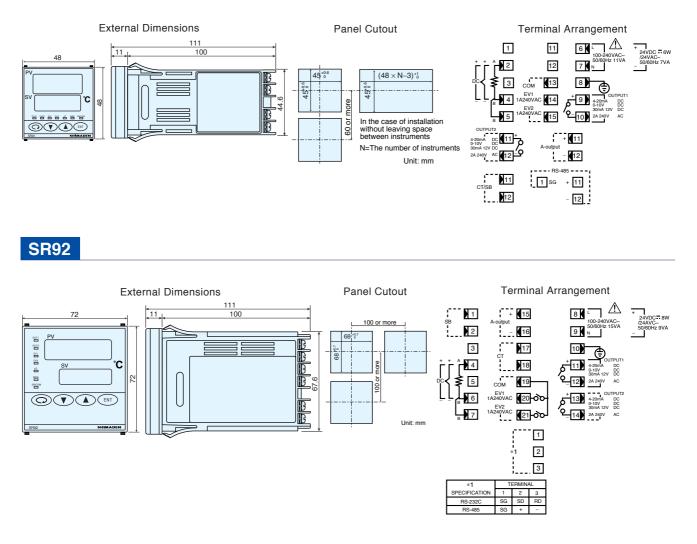
ITEM			CO	DE					SPECIFICATION	S	
	SR93-								MPU-Based Auto-Tuning PID Digital Controller, DIN H96 × W96 × D110mm		
SERIES	SR94-		-						MPU-Based Auto-Tuning PID Digital Controller, DIN H96 × W48 × D110mm		
									Thermocouple: B, R, S, K, E, J, T, N, PLII, Wre	95-26 {	U, L (DIN 43710)}
		8	N	lti inp	<del>.</del>				R.T.D.: Pt100Ω /JPt100Ω		
		0	iviui	μπρ	Jui				Voltage: -10~10, 0~10, 0~20,	For	voltage and current input:
INPUT									0~50, 10~50, 0~100mV DC	Sca	ling Possible
		4							Current (mA): 0~20, 4~20mA DC	Ran	ge: -1999~9999
		-							Receiving impedance: $250\Omega$	-	
		6							Voltage (V): -1~1, 0~1, 0~2, 0~5, 0~10V DC	Note	e: Inverse scaling
									Load resistance: $600\Omega$ max.		is not possible
			Y-						Contact: 1a, Contact capacity: 240V AC 2A/res	sistive	load
			-						Proportional cycle: 1~120 sec.		
			1-						Current: 4~20mA DC		
CONTROL		(1)							Load resistance: $600\Omega$ max.		
		( )	P-						SSR drive voltage: 12V±1.5V DC/30mA max.		
									Proportional cycle: 1~120 sec.		
			V-						Voltage: 0~10V DC		
					1				Load current: 2mA max.		
				N-					None		
				Y-					Contact: 1a, Contact capacity: 240V AC 2A/res	istive	load
			ł						Proportional cycle: 1~120 sec. Current: 4~20mA DC		
CONTROL		(2)		I-			Current: 4~20mA DC Load resistance: 600Ω max.				
(OPTION)		. ,	-						SSR drive voltage: 12V±1.5V DC/30mA max.		
				P-					Proportional cycle: 1~120 sec.		
			ł						Voltage: 0~10V DC		
				V-					Load current: 2mA max.		
					90-				100~240V AC±10%, 50/60Hz		
POWER S	UPPLY				08-				24V AC/DC±10%, 50/60Hz		
				I		0			None		
					ľ				Event output (2a) Ev1, Ev2		
						1			Contact capacity: 240V AC 1A/resistive load		
EVENT O	JTPUT/ BREAK AL/	ARM	(OP1	ΓΙΟΝ	I)	2			Event output (Ev1) + Heater break alarm (with C1	-30A)	Note: Available only
			<b>、</b> -		í l	2				00/1)	when control output (1)
						3			Event output (Ev1) + Heater break alarm (with C1	50A)	is Y or P is selected.
							00		None		
							30		Voltage: 0~10mV DC, Output resistance: 10Ω		
	Ana	alog (	outpu	t			40		Current: 4~20mA DC, Load resistance: 300Ω r	nax.	
							60		Voltage: 0~10V DC, Load current: 2mA max.		
	01	D:					00		DI (set value bias, STBY, or ACT) 1 point, Non-volta	age cor	ntact or Open collector input
	50	Bias	/ DI				08		Open collector input rating: approx. 5V/1mA max.		
OPTION							00		Voltage: 0~10mV DC, Output resistance: 10Ω		
							38		DI (set value bias, STBY, or ACT) 1 point		
	Analog output +			48		Current: 4~20mA DC, Load resistance: 300Ω max.					
SV Bias / DI		10		DI (set value bias, STBY, or ACT) 1 point							
							68		Voltage: 0~10V DC, Load current: 2mA max.		
									DI (set value bias, STBY, or ACT) 1 point		
	Cor	mmu	nicati	on			05		RS-485 (Shimaden standard protocol / MODBI		
							07		RS-232C (Shimaden standard protocol / MOD	BUS (I	RTU / ASCII))
REMARKS	3							0	Without		
	-							9	With (Please consult before ordering.)		

### Note:

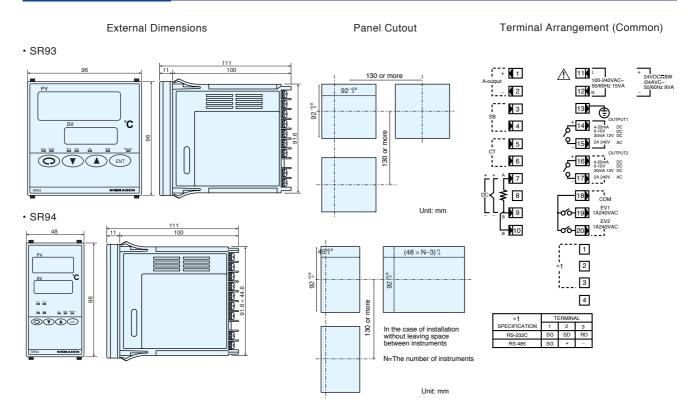
When you purchase a two-output type controller and use it in a one output capacity, larger overshooting or undershooting may happen as a result of integral operation. Therefore, we recommend you to choose a one-output type.

The cause of the above-mentioned problem is that the positional relationship between the proportional band (PB) and the set value (SV) of a one-output type controller differs from that of a two-output type.





## SR93 AND SR94



## MEASURING RANGE CODES

	Input 1	Гуре	Code	Measuring range (°C) Measuring range (°F)
		B *1	01	0 ~ 1800 °C 0 ~ 3300 °F
		R	02	0 $\sim$ 1700 °C 0 $\sim$ 3100 °F
		s	03	0 $\sim$ 1700 $^\circ$ C 0 $\sim$ 3100 $^\circ$ F
		K	04 *2	-199.9 $\sim$ 400.0 °C -300 $\sim$ 750 °F
		K	05	0.0 $\sim$ 800.0 °C 0 $\sim$ 1500 °F
		K	06	0 $\sim$ 1200 °C 0 $\sim$ 2200 °F
		E	07	0 $\sim$ 700 °C 0 $\sim$ 1300 °F
		J	08	0 $\sim$ 600 °C 0 $\sim$ 1100 °F
	Thermo-	Т	09 *2	-199.9 $\sim$ 200.0 $^\circ$ C -300 $\sim$ 400 $^\circ$ F
	couple	N	10	0 $\sim$ 1300 °C 0 $\sim$ 2300 °F
		PLII *3	11	0 $\sim$ 1300 °C 0 $\sim$ 2300 °F
		WRe5-26 *4	12	0 $\sim$ 2300 $^\circ$ C 0 $\sim$ 4200 $^\circ$ F
		U *5	13 *2	-199.9 $\sim$ 200.0 °C -300 $\sim$ 400 °F
		L *5	14	0 $\sim$ 600 °C 0 $\sim$ 1100 °F
ort		K *6	15	10.0 $\sim$ 350.0 K
Ë.		AuFe-Cr *7	16	0.0 $\sim$ 350.0 K
Multi-input		K *6	17	10 $\sim$ 350 K
Ē		AuFe-Cr *7	18	0 $\sim$ 350 K
			31	-200 $\sim$ 600 °C -300 $\sim$ 1100 °F
		Pt100	32	-100.0 $\sim$ 100.0 $^\circ\mathrm{C}$ -150.0 $\sim$ 200.0 $^\circ\mathrm{F}$
		FIIOU	33	-50.0 $\sim$ 50.0 $^\circ$ C -50.0 $\sim$ 120.0 $^\circ$ F
	R.T.D.		34	$0.0~\sim~200.0~^\circ\mathrm{C}$ $0.0~\sim~400.0~^\circ\mathrm{F}$
			35	-200 $\sim$ 500 °C -300 $\sim$ 1000 °F
		JPt100	36	$-100.0 \sim 100.0$ °C $-150.0 \sim 200.0$ °F
		0.1100	37	$-50.0 \sim 50.0$ °C $-50.0 \sim 120.0$ °F
			38	$0.0 \sim 200.0~^{\circ}\text{C}$ $0.0 \sim 400.0~^{\circ}\text{F}$
		-10 ~ 10	71	Scaling possible
	Maltana	0~10	72	
	Voltage	$0 \sim 20$	73	Owing to scaling function, any measuring range
	(mV)	$0 \sim 50$	74	can be set within the following range.
		$10 \sim 50$	75	san be set within the following range.
<u> </u>		0~100	76	Scaling range: -1999 to 9999 counts
		-1~ 1	81	Span: 10 to 5000 counts on condition of
		$0 \sim 1$ $0 \sim 2$	82	lower side < higher side
Vo	oltage (V)		83	iowei side < nighei side
		$0 \sim 5$ $1 \sim 5$	84	
		$1 \sim 5$ $0 \sim 10$	85	
-			86	
Cu	rrent (mA)		91	
	( )	$_{4}\sim$ 20	92	

### Series SR90

\*1 Thermocouple:

B: Accuracy guarantee not applicable to 400°C (752°F) and below.

\*2 Thermocouple

K, T, U: Accuracy guarantee not applicable to temperature below -100°C  $\pm(0.7\%~FS$  + 1 digit)

\*3 Thermocouple

PLII: Platinel

\*4 Thermocouple

Wre5-26: A product of Hoskins

\*5 Thermocouple U, L: DIN 43710

\*6. Thermocouple K (Kelvin) accuracy

Temperatu	ire ra	nge	External CJ	Internal CJ

10.0 ~	30.0 K ±(2.0%FS + [CJ error X 20] K + 1K)	
30.0 ~	70.0 K $\pm$ (1.0%FS + [CJ error X 7] K + 1K)	
70.0		

70.0 ~	170.0 K ±(0.7%FS	$^{+}$	[CJ error X	3] K +	1K)
	$070 0 K \pm 0 F0 F0$		C Lower V 1	FIV I	11/

170.0 ~ 270.0 K ±	(0.5%FS +	[CJ error X	1.5] K + 1K)
270.0 ~ 350.0 K ±	(0.3%FS +	[CJ error X	1] K + 1K)

\*7. Thermocouple Metal-chromel (AuFe-Cr) (Kelvin) accuracy Temperature range External CJ Internal CJ

- $\begin{array}{l} 0.0 \sim & 30.0 \ \text{K} \pm (0.7\% \text{FS} + [\text{CJ error X} \quad 3] \ \text{K} + 1 \text{K}) \\ 30.0 \sim & 70.0 \ \text{K} \pm (0.5\% \text{FS} + [\text{CJ error X} \quad 1.5] \ \text{K} + 1 \text{K}) \\ 70.0 \sim & 170.0 \ \text{K} \pm (0.3\% \text{FS} + [\text{CJ error X} \quad 1.2] \ \text{K} + 1 \text{K}) \\ 170.0 \sim & 280.0 \ \text{K} \pm (0.3\% \text{FS} + [\text{CJ error X} \quad 1] \ \text{K} + 1 \text{K}) \end{array}$
- 280.0 ~ 350.0 K ±(0.5%FS + [CJ error X 1] K + 1K)

NOTE:

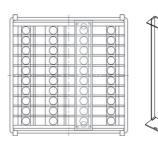
Unless otherwise specified, the measuring range will be set as listed below during the shipment from the factory.

Input	Specification/Rating	Measuring range
Multi-input	K thermocouple	$0.0 \sim 800.0^\circ C$
Voltage (V)	0 ~ 10V DC	0.0 ~ 100.0
Current (mA)	4 ~ 20mA DC	0.0 ~ 100.0

# TERMINAL COVER (AVAILABLE SEPARATELY)

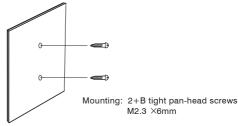
Ν	Nodel	Mounting
SR91	QCR001	One-touch mount
SR92	QCR002	One-touch mount
SR93	QCR003	One-touch mount

Thickness: 1 mm



Model		Mounting
I SRUA	QCR004 (Individual mounting)	Plus screw, B tight, M2.3 $\times$ 6 - 2 pcs.
	QCR005 (Tight-lock coupling)	Plus screw, B tight, M2.3 $\times$ 6 - 4 pcs.

Material/Appearance: PVC/transparent Thickness: 1 mm



### 🕂 Warning

• The SR90 series is designed for the control of temperature, humidity and other physical values of general industrial equipment. (It is not to be used for any purpose which regulates the prevention of serious effects on human life or safety.)

### \land Caution

• If the possibility of loss or damage to your system or property as a result of failure of any part of the process exists, proper safety measures must be made before the instrument is put into use so as to prevent the occurrence of trouble.

#### ISO9001 · ISO14001



(The contents of this brochure are subject to change without notice.)

